

REACT

V, M, P, P-X, ALS

Modbus settings

20231005

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Modbus settings for REACT ALS, V, V-SR, M, P, P-X and P-X-SR

Recommendations for communication via Modbus

The parameters are arranged in 2 memory categories.

One memory is a temporary memory (RAM) and the other memory is a permanent memory (EEPROM).

RAM

The temporary memory is used for e.g. the actual value of the current measured flow and the damper position is saved. These values change frequently and, in the event of a power failure, there is no information about the most recent value remaining in the RAM memory. This memory cannot become full, rather it is possible to write to the memory an infinite number of times.

EEPROM

The permanent memory retains its information, even following a power failure. Examples of parameters in this memory include the established setpoint for min. flow/max. flow or the size that is set in the "Vnom" damper. This memory has a max. limit of 1 million (1,000,000) writes, after which the memory is full and it is not possible to write to it any more.

The recommendation is to limit the number of writes to EEPROM as much as possible, but if e.g. the setting for min. flow (Address 105 or 120) is changed 20 times in a day (10 changes of e.g. occupancy mode in the room), this will "only" equate to 7,300 writes over a year. (20 x 365 days = 7,300 writes). It is important to only write to EEPROM in the event of changes.

Transfer protocol

Protocol:	Modbus RTU
Number of nodes max.	128
Communication rate:	1200 / 2400 / 4800 / 9600 / 19200 / 38400
Bit sequence:	MSB / LSB
Bit format:	1 start bit, 8 data bits, 2 stop bits, no parity 1 start bit, 8 data bits, 1 stop bit, even parity 1 start bit, 8 data bits, 1 stop bit, odd parity
Termination resistance:	120 Ohm (external)
Delay:	Some master products need a specific time to switch from transfer mode to receiver mode. The delay time can be set in increments of 3 ms. Max. 765 ms (255 × 3 ms)
Response time:	≤ 10 ms + delay
Standard communication parameters: Communication setting: 14	1 start bit 19200 baud 8 data bits 1 stop bit Even parity Delay 0 ms

Values for communication rate, parity, stop bits and delay can be changed.

Function code

Function code	Name	Description
03h	Read holding address	Unit parameter / actual read value (integer/floating point)
06h	Write individual holding address	Unit parameter / single words written

Error codes

Error code	Name	Description
01h	Illegal function	The received function code is not allowed to be used in communication with the unit
02h	Illegal data address	The requested register is not available. Alternatively, the register is only a read address
03h	Illegal data value	The written value is not permitted
06h	Slave device busy	The unit is busy

Modbus Register

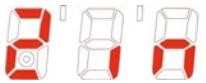
Holding address

- EEPROM memory is permanent (max. 1 million writes)
- RAM memory is non-permanent

Name	Address	Memory	Value	r/w	Description
Set point	0	RAM	0...10000	r/w	Set point [%] 0 = 0%, 10000 = 100% Only read value if address 122 = '0, 3'
Forced control	1	RAM	0...4	r/w	'0' Auto mode, test/forced control not active '1' Open '2' Closed '3' Set min. value '4' Set max. value Only read value if address 122 = '0, 3'
Relative position	4	RAM	0...10000	r	Relative position [%] 0 = 0%, 10000 = 100%
Absolute position	5	RAM	0...65000	r	Absolute position [°] 0...65000
Relative value	6	RAM	0...10000	r	Relative value [%] 0 = 0%, 10000 = 100%
Absolute value	7	RAM	0...65535	r	Absolute value [m^3/h][l/s][Pa][inH ₂ O $\times 10^{-3}$] See address 201
Feedback signal	10	RAM	0...10000	r/w	Feedback signal [mV] 0...10000 Only read value if address 122 = '0, 1'
Software version	103	EEPROM		r	Software version
Min relative value	105	EEPROM	0...10000	r/w	Min. value in % of nominal value [%] 0 = 0%, 10000 = 100%
Max relative value	106	EEPROM	0...10000	r/w	Max. value in % of nominal value [%] 0 = 0%, 10000 = 100%
Position for dropped communication	108	EEPROM	0...2	r/w	Function after 120 s dropped communication '0' Not active '1' Damper closes '2' Damper opens
Min. absolute value	120	EEPROM	0...65535	r/w	Min. value [l/s][m^3/h][Pa][inH ₂ O $\times 10^{-3}$] See address 201
Max. absolute value	121	EEPROM	0...65535	r/w	Max. value [l/s][m^3/h][Pa][inH ₂ O $\times 10^{-3}$] See address 201
Set point function	122	EEPROM	0...3	r/w	Value
					Analogue in 0(2)...10 V
					Absolute value 0(2)...10 V
					Set point controlled via Modbus address 0) 0% = Min. value 100% = Max. value
					Set point controlled via Modbus (address 0) 0% = Min. value 100% = Max. value
					Feedback signal controlled via Modbus (address 10) 0% = Min. value 100% = Max. value
					Analogue in 0(2)...10 V
					Feedback signal controlled via Modbus (address 10) 0% = Min. value 100% = Max. value
Modbus address	130	EEPROM	1 - 247	r/w	Modbus address 1 – 247
Unit*	201	EEPROM	0...3	r/w	'0' [l/s] '1' [m^3/h] '2' [Pa] '3' [inH ₂ O $\times 10^{-3}$]

* Product dependent

Communication settings

Function	Description														
Adr	 <p>Enables you to set the actuator's Modbus address, by turning the "edit wheel". It is possible to set the address from 1 till 247. If you turn the value selector to end stop "+", the display will show a "2". This makes it possible to select the second level. If you select the second level, this is indicated in the display by a small circle.</p> <p>The following functions are available at the second level:</p> <table> <tbody> <tr> <td>Flow</td> <td>Return to previous level</td> </tr> <tr> <td>V_{min}</td> <td>Not used.</td> </tr> <tr> <td>V_{max}</td> <td>Not used.</td> </tr> <tr> <td>Test</td> <td>Not used.</td> </tr> <tr> <td>Mode</td> <td>Shows the angle of the rotation (0...255 digital 0....100%)</td> </tr> <tr> <td>Adr.</td> <td>Used for selecting communication settings for Modbus. See table below.</td> </tr> <tr> <td>V_{nom}</td> <td>Used for setting response delay for the Modbus communication</td> </tr> </tbody> </table>	Flow	Return to previous level	V _{min}	Not used.	V _{max}	Not used.	Test	Not used.	Mode	Shows the angle of the rotation (0...255 digital 0....100%)	Adr.	Used for selecting communication settings for Modbus. See table below.	V _{nom}	Used for setting response delay for the Modbus communication
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Mode	Shows the angle of the rotation (0...255 digital 0....100%)														
Adr.	Used for selecting communication settings for Modbus. See table below.														
V _{nom}	Used for setting response delay for the Modbus communication														

Display number	EEPROM value	Communication rate	Parity	Stop bits
1 ²	0	1200	None	2
2 ²	1	1200	Even	1
3 ²	2	1200	Odd	1
4	3	2400	None	2
5	4	2400	Even	1
6	5	2400	Odd	1
7	6	4800	None	2
8	7	4800	Even	1
9	8	4800	Odd	1
10	9	9600	None	2
11	10	9600	Even	1
12	11	9600	Odd	1
13	12	19200	None	2
14 ³	13	19200	Even	1
15	14	19200	Odd	1
16	15	38400	None	2
17	16	38400	Even	1
18	17	38400	Odd	1
19 ²	18	1200	None	1
20	19	2400	None	1
21	20	4800	None	1
22	21	9600	None	1
23	22	19200	None	1
24	23	38400	None	1

² Limited data length per reading of max. 8 addresses

³ Default setting